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Control of Dynamic Systems
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System Dynamics: Fundamental Behavior Patterns

Introduction to System

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~~A Brief Introduction to~~

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| Yuval Noah Harari | Talks

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Systems Dynamics Models to

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guide covers the following chapters: 13. The full step-by-step solution to problem in System Dynamics were answered by , our top Engineering and Tech solution expert on 01/03/18, 09:39PM.

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The solution is $x(t) = 0.25e^{-2t} + 0.25 + 0.5t - e^{-t} + 2e^{-t} + 3e^{-t}$ [r,p,k] = residue([4,3],[1,6,34,0])
The result is r = [-0.0441 - 0.3735i, -0.0441 + 0.3735i, 0.0882], p = [-3.0000 + 5.0000i, -3.0000 - 5.0000i, 0], and k = []. The solution is $x(t) = (0.0441 - 0.3735i)e^{(-3.0000 + 5.0000i)t} + (0.0441 + 0.3735i)e^{(-3.0000 - 5.0000i)t} + 0.0882e^{-t} + 0.25e^{-2t} + 0.25 + 0.5t$

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 $0.3735j)e^{(3+5j)t} + (0.0441 + 0.3735j)e^{(3-5j)t} + 0.0882$
The solution is $x(t) = 2e^{3t} (0.0441 \cos 5t + 0.3735 \sin 5t) + 0.0882$ (continued on the next page)

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= 0:5 when $t = 500$ years,
then $0:5 = e^{5500b}$, which
gives $b = \ln(0:5)/5500 =$
 $1:2603 \ 104$. (b) Solve for t
to obtain $t =$
 $\ln[C(t)/C(0)]/b$ using $C(t)/C(0)$
 $= 0:9$ and $b = 1:2603 \ 104$.
The answer is 836 years.

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...

While other subjects, such
as Newtonian dynamics and
electrical circuit theory,
also deal with.

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The characteristic equation
derived earlier becomes 2?2

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$2+3 \pm \sqrt{1-0.01} \pm 0.3 \pm 1=0$
whose roots are ± 26.18 and ± 3.82 . The dominant time constant is $1/3.82=0.262$, and thus we would expect the steady-state response to be reached in about $4(0.262)=1.04$ s. The scope plot confirms this. 16.

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2.3 a) $\int_0^t x^3 dx = \frac{1}{4} x^4 \Big|_0^t = \frac{1}{4} t^4$
 $\frac{d}{dt} \left(\frac{1}{4} t^4 \right) = t^3$
 $\int_0^t x^3 dx = \frac{1}{4} t^4$
 $\frac{d}{dt} \left(\frac{1}{4} t^4 \right) = t^3$
 $\int_0^t x^3 dx = \frac{1}{4} t^4$
 $\frac{d}{dt} \left(\frac{1}{4} t^4 \right) = t^3$
Let $C = \frac{1}{4} t^4$
Solve for x to obtain $x = \sqrt[4]{4C}$
b) $\int_0^t x^{10} dx = \frac{1}{11} x^{11} \Big|_0^t = \frac{1}{11} t^{11}$
 $\frac{d}{dt} \left(\frac{1}{11} t^{11} \right) = t^{10}$

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...

The solution for the forced
response is $x_{\text{forced}}(t) =$

$$0.0034te^{-3t}\sin$$

$$5t + 0.0066te^{-3t}\cos 5t +$$

$$0.0026e^{-3t}\sin$$

$$5t + 2.308 \times 10^{-4}e^{-3t}\cos 5t +$$

$$0.00796 \sin$$

$$0.866te^{-2.308 \times 10^{-4}}\cos 0.866t$$

The initial condition $x(0) = 0$ is not exactly satisfied by this expression because of the limited number of digits used to display it.

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III ...

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These roots correspond to

the polynomial equation $(s +$

$1 + j)(s + 1 - j) = (s +$

$1)^2 + 1 = s^2 + 2s + 2 = 0$ or

$10s^2 + 20s + 20 = 0$ Compare

this with the system's

characteristic equation

obtained from the

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denominator of the transfer function: $10s^2 + (3 + KD)s + KP = 0$ Thus $KP = 20$ and $3 + KD = 20$, or $KD = 17$.

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1.13 Speed = $40 (5280) / 3600 = 58.6667$ ft/sec. Frequency = $58.6667 / 30 = 1.9556$ times per second. 1.14 $x = 0.005 \sin 6t$, $\dot{x} = 0.005 (6) \cos 6t = 0.03 \cos 6t$. Velocity amplitude is 0.03 m/s. $x = 0.03 \sin 6t = 0.18 \sin 6t$. Acceleration amplitude is 0.18 m/s².

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for you to be successful. As
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recommend that you have
astonishing points.
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difficulty as arrangement
even more than new will have
the funds for each success.
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The subject of system
dynamics deals with
mathematical modeling and
analysis of devices and
processes for the purpose of
understanding their time-

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