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Angular speed of the crank = $2 \text{ N}/60 = 2 \times 2000/60 = 209.4 \text{ rad/s}$
(vA)O = $\omega \times \text{radius} = 209.4 \times 0.05 = 10.47 \text{ m/s}$. First draw vector oa. (diagram a) Next add a line in the direction ab (diagram b) Finally add the line in the direction of ob to find point b and measure ob to get the velocity. (diagram C).

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Anna University Topic
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masses 2 What is
balancing of rotating

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This is the very first
lecture of the lecture
series for subject

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lecture, I have

described how the

dynamics of Machine

was deri...

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frames as complex

systems. Typical

dynamic effects, such

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of machines and
determining of
characteristics values
--Dynamics of
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rigid bodies
--Foundation and
isolation of vibrations
--Torsional vibrations
and oscillators having
a chain-structure

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Equations required to solve problems $h = (r_2 - r_1) \times y \times S_2 - S_1 =$

$h.s, s = S_2 - S_1$ $h = S_2 - S_1$ $r_2 - r_1 \times x y$

Neglecting obliquity effect, moment due to weight at minimum position, $M g + S_1 =$

$2FC_1 \times x y$, similarly for maximum position

$M g + S_2 = 2FC_2 \times x y$

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$S_2 - S_1 = 2(FC_2 - FC_1) \times x y$, substitute

$S_2 - S_1 = h.s$, $s =$

$S_2 - S_1 = r_2 - r_1 \times [x y]^2$

$FC = FC_1 + (FC_2 -$

$FC_1) \frac{r_2 - r_1}{r_2 - r_1} = FC_2$

$+ (FC_2 - FC_1) \frac{r_2 - r_1}{r_2 - r_1}$

$r_2 - r_1$ We can

neglect obliquity effect
unless it is mentioned

...

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$r_B = r_C = 0.3 \text{ m}$; $m_1 = 150 \text{ kg}$; $m_2 = 180 \text{ kg}$; $c = 2/3$; $r_A = r_D = 0.6 \text{ m}$; $N = 300 \text{ r.p.m.}$
or $\omega = 2 \times 300 / 60 = 31.42 \text{ rad/s}$. We know that the equivalent mass of the rotating parts to be balanced per cylinder at the crank pin, $m = m_B = m_C = m_1 + c.m_2 = 150 + 2/3 \times 180 = 270 \text{ kg}$.

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Magnitude and direction of the balancing masses.

Let m_A and $m_D =$
Magnitude of the
balancing masses

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textbook written for
engineers and
students studying

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undergraduate and
postgraduate levels.

Its aim is to allow
readers to learn and
gain a comprehensive
understanding of the
dynamics of rotating
machines by reading,
problem solving, and
experimenting with
rotor models in
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a branch of the theory of machines and mechanisms that studies the motion of machines and mechanisms, taking into account the forces acting on them.

The dynamics of machines and mechanisms deals

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with the following
basic problems:
definition of the laws
of motion of the
components of
mechanisms, control
of the motion of the
components,
determination of
frictional losses,
determination of the
reactions in kinematic
pairs, and balancing
of machines and

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